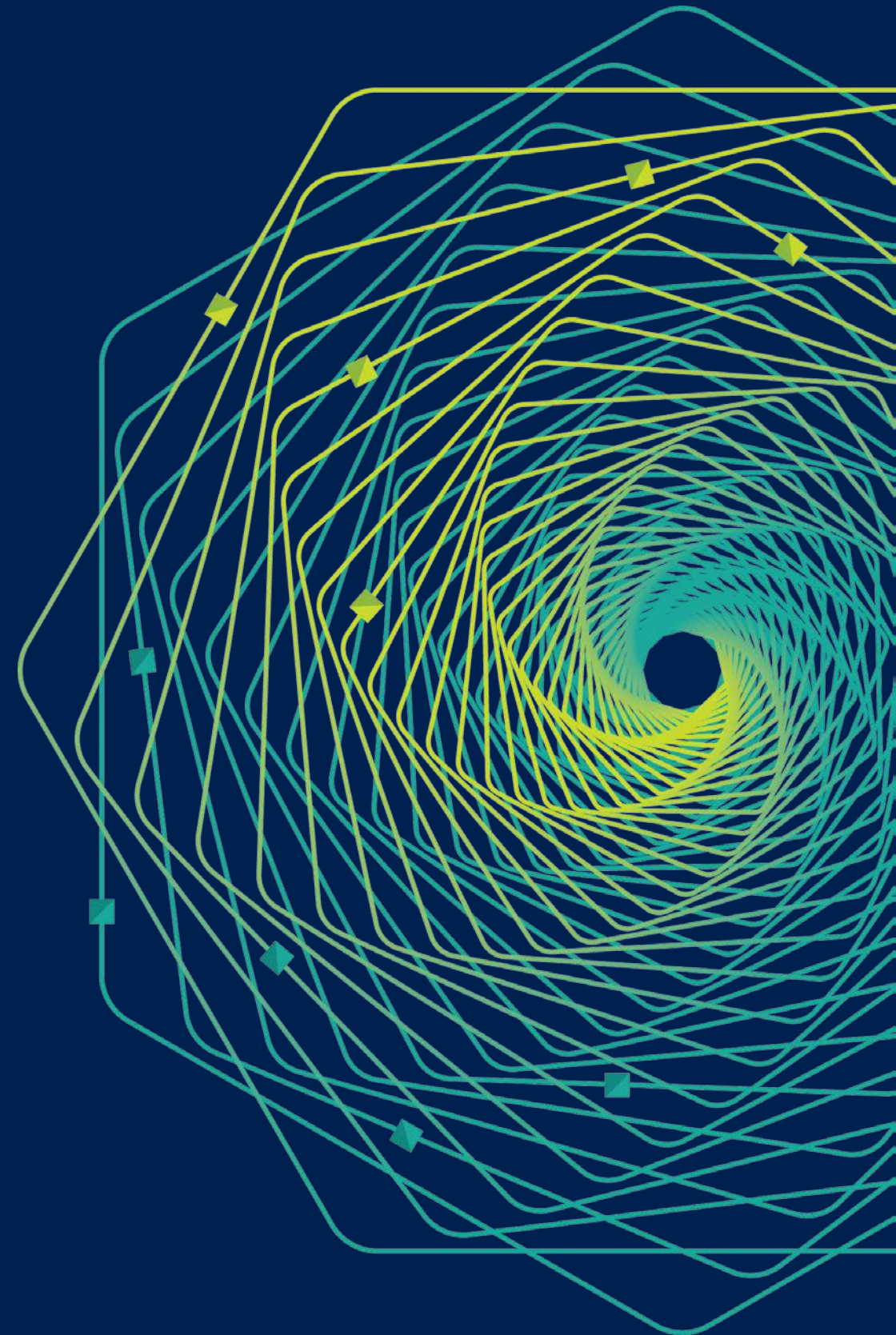


# Research Faculty Summit 2018

Systems | Fueling future disruptions





# Network Decomposition

Mung Chiang

Dean, College of Engineering, Purdue University

Founding Director, EDGE Lab, Princeton University



@OpenFog #fogcomputing

# Network Decomposition

- **Vertical & Horizontal Decomposition:**
  - Who does what, at what timescale, how to glue them together?
  - Allocation of functions, not just resources
  - **Vertical: Layering as decomposition**
  - **Horizontal: Cloud – Edge/Fog as decomposition**
  
- **Architecture supports Applications:**
  - Source-channel separation: Digital communication
  - TCP/IP: Internet applications
  - **Edge/Fog: IoT / 5G / Dispersive AI**

The Princeton  
**EDGE** Lab

2009

Distribute functions to network edge



2015

Decompose functions along Cloud-2-Things Continuum



# Interfaces



Massive storage  
Heavy duty computation  
Global coordination  
Wide-area connectivity

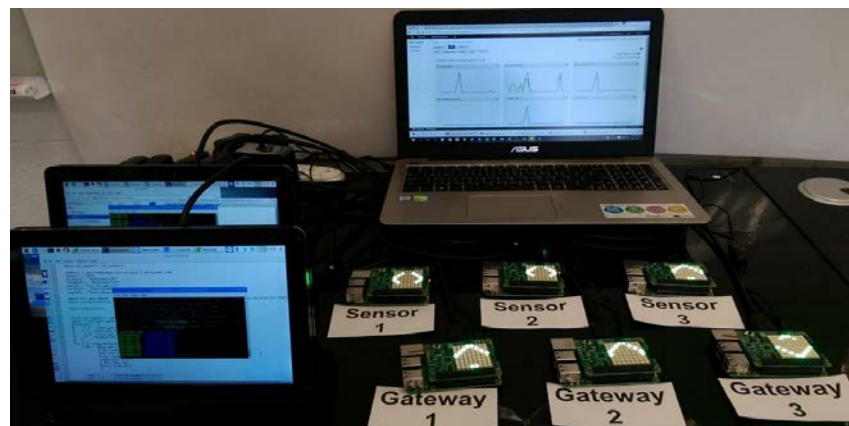
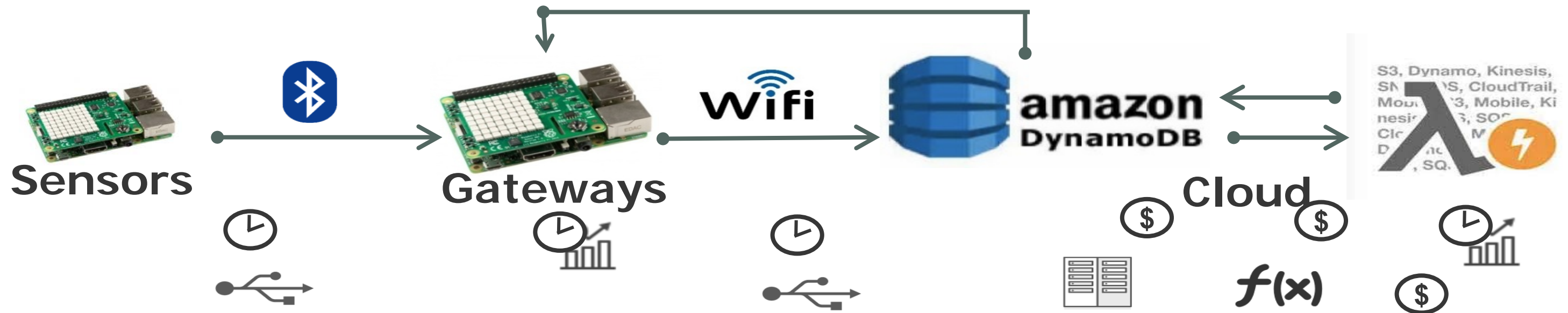


Real time processing  
Rapid innovation  
User-centric  
Edge resource pooling

# Applications to Dispersive AI

- Design machine learning algorithms that support **fast responses**
  - Enable IoT systems with intelligence here and now
- **Decompose machine learning** into multiple geographically distributed components, collectively or jointly operating
  - Optimize communication costs and centralized data processing costs
  - Make best use of local/proximal resources
- **Proactively pre-position content and computing**
  - Parallel successive refinement for streaming mining
  - Reduce infrastructure costs and improve quality of experience

# Testing Decompositions of Machine Learning

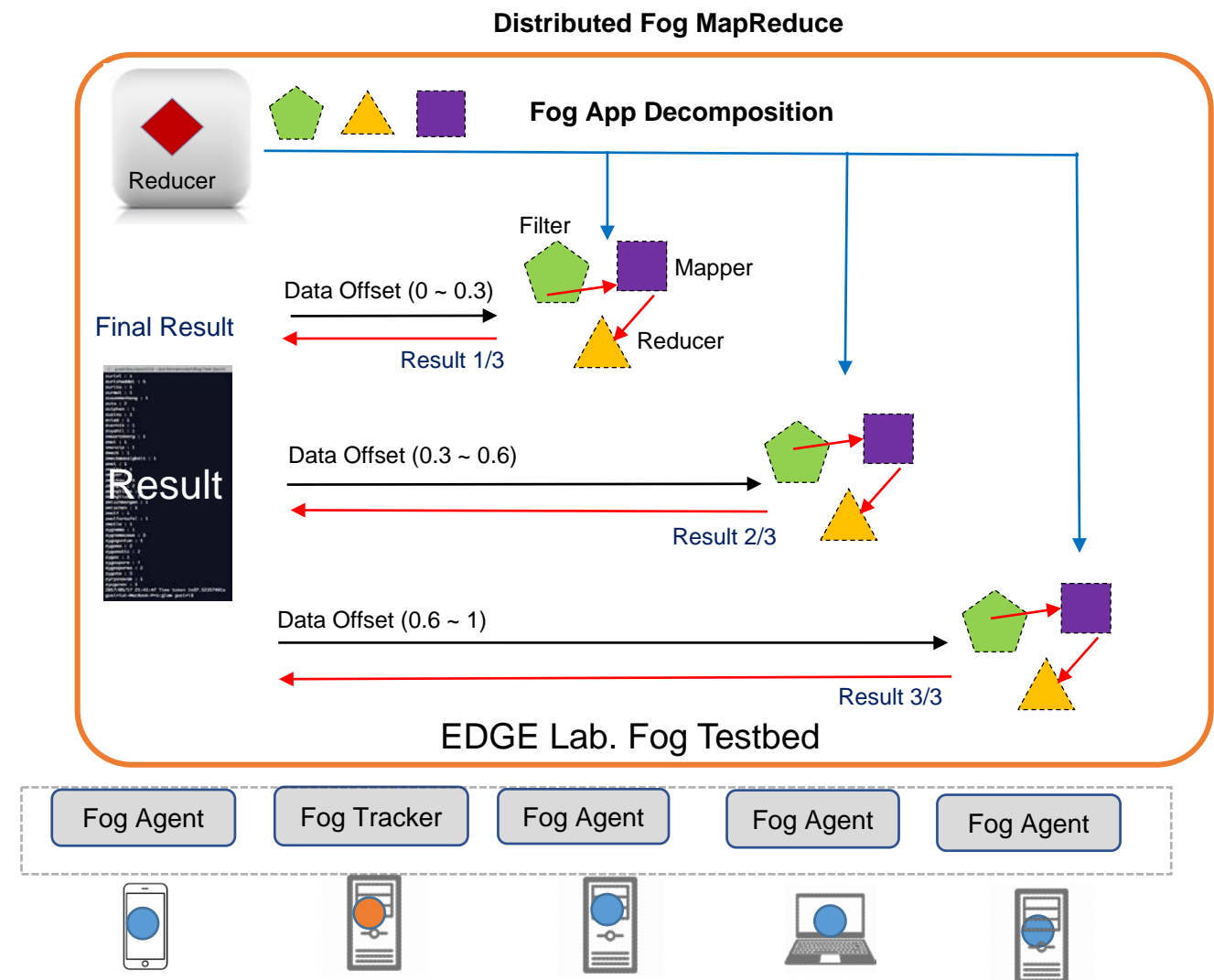
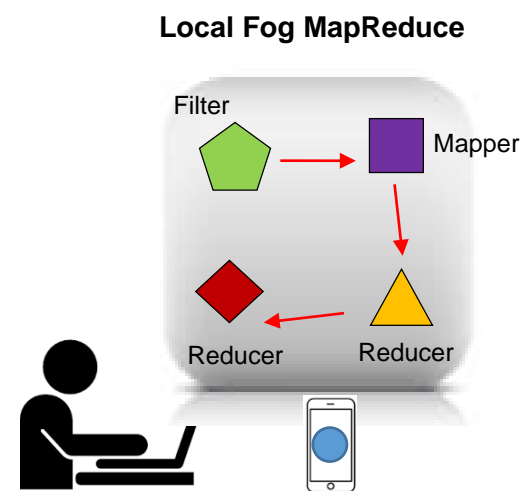


- Specialized testbed developed
- Linear regression decomposition: 70% reduction in data transmission
- Demonstrations: IEEE FWC'17, ACM SenSys'17 NYC Media Lab Summit'17.

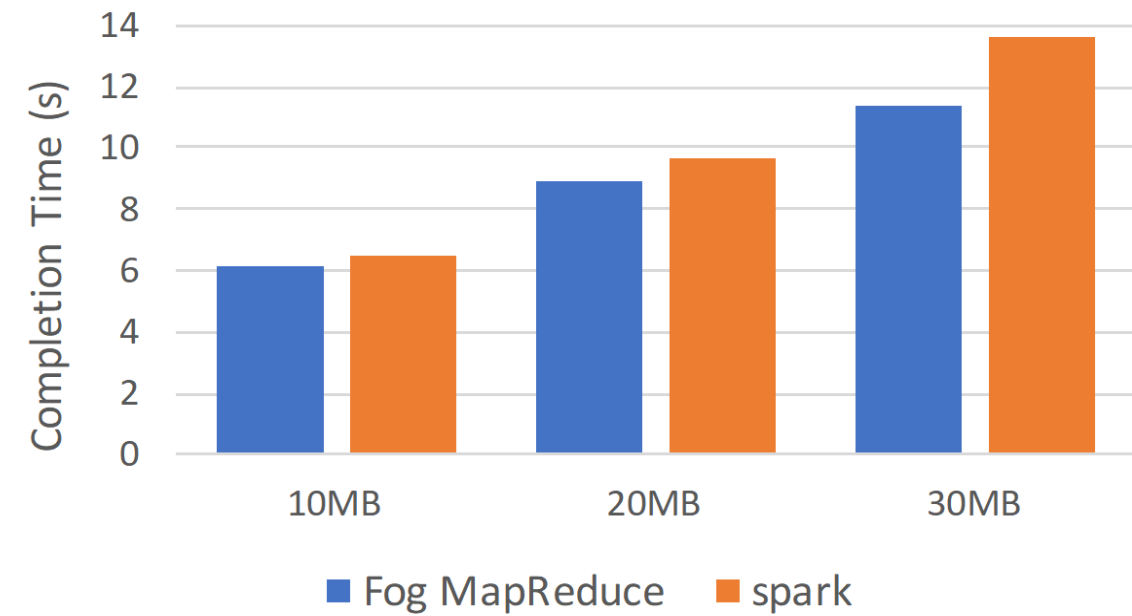
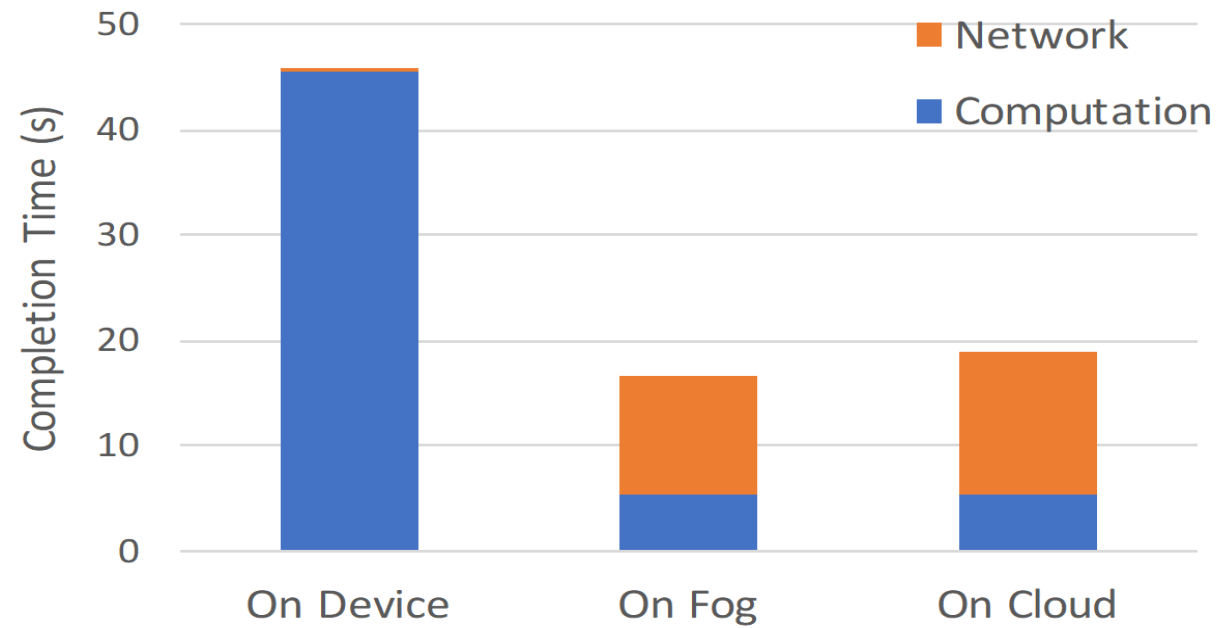


# New MapReduce

- Re-visit MapReduce for Fog environment
  - Coordination & consistency
  - Robustness through redundancy
  - Computation decomposition
  - Task placement and scheduling along C2T
  - Automating deployment
- Prototype provides primary MapReduce APIs
  - Filter
  - Map
  - Reduce
  - ReduceByKey
  - MapByKey



# Simple Example: Counting Words in a File



# Unique Features in Edge/Fog

- Heterogeneity/Under-organization of resources/devices
- Variability/Volatility in availability/mobility
- Bandwidth/Battery constraints
- Proximity to sensors/actuators

# Two Toy Examples

- Drone Camera Network
  - Aakanksha Chowdhery, Shirley Wang
- Personalized Placement Learning in AR/VR
  - Surin Ahn, Maria Gorlatova, Parinaz Naghizadeh

# Outdoor Live Coverage

- Stadiums use 30-50 cameras to capture games nationally broadcast

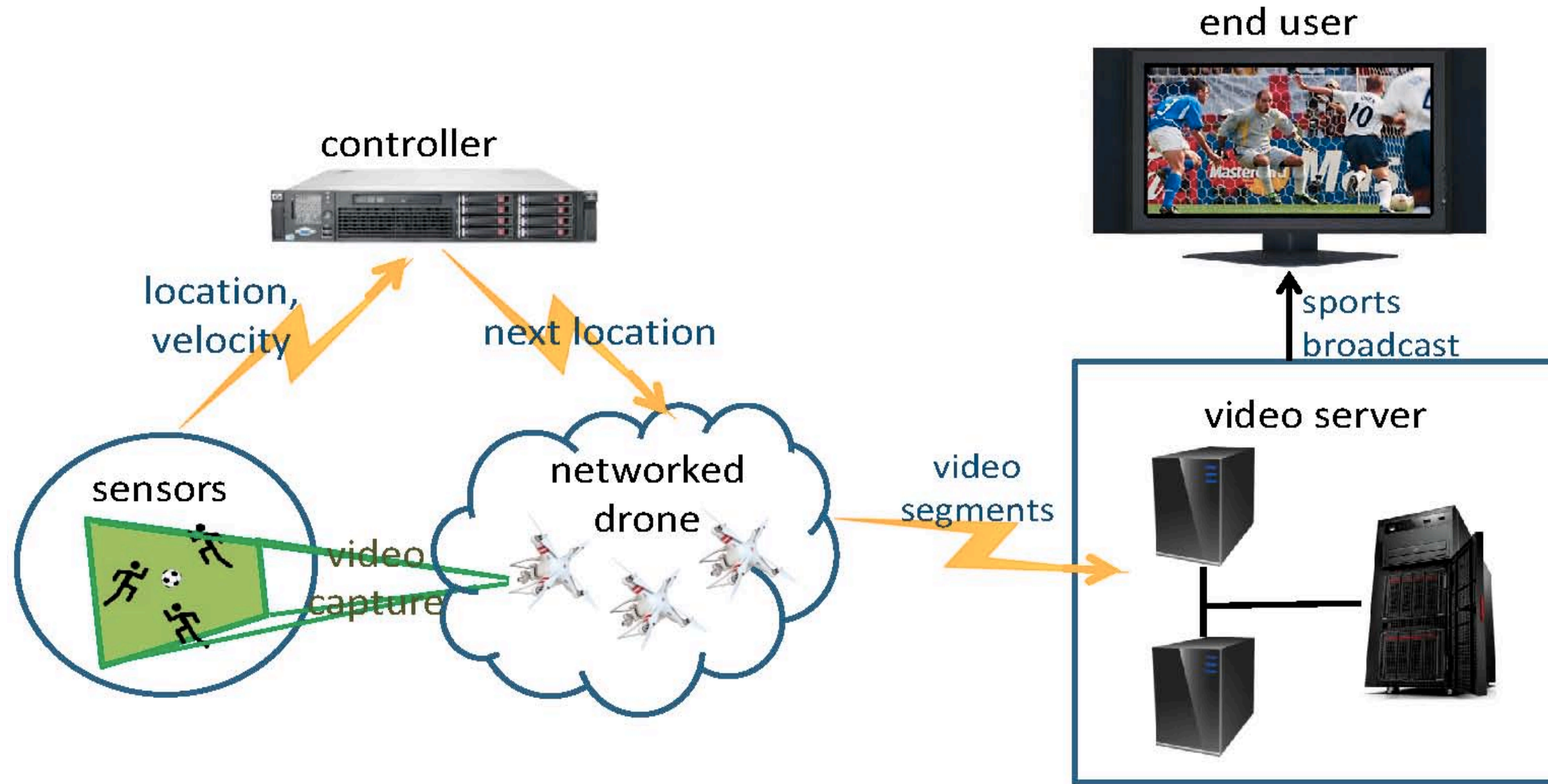


- NFL recently introduced cameras over crosswires: SkyCam, SpiderCam

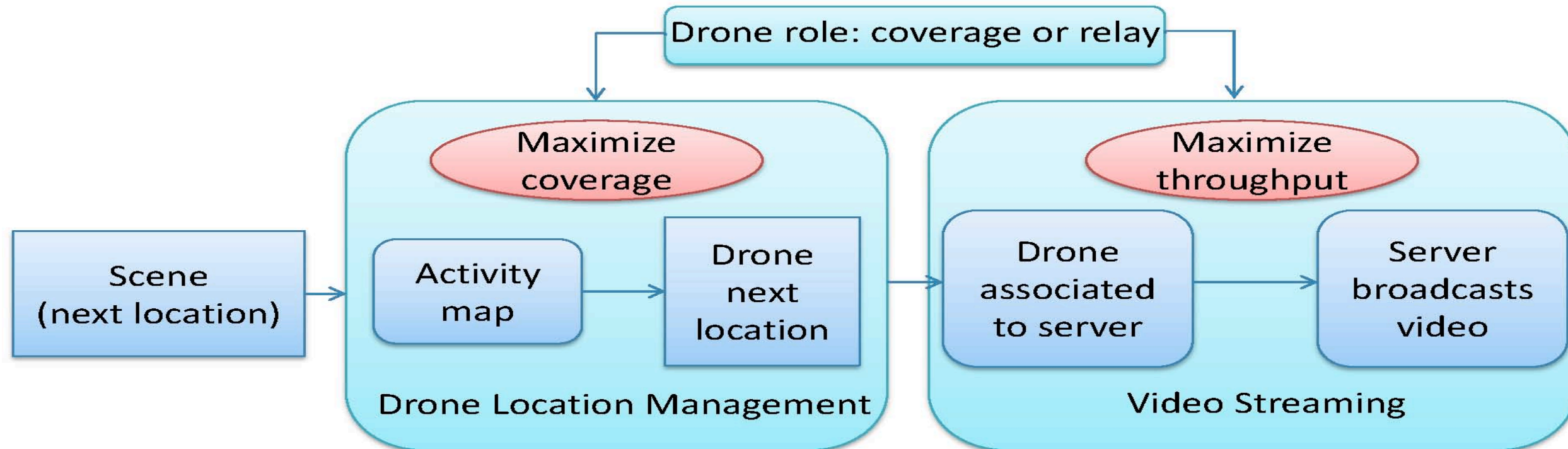
# Network Decomposition

- Distributed
  - Make decision locally; low latency
  - Suboptimal: all drones prioritize covering the most important scene
- Centralized
  - Cloud makes decisions, cost benefits and efficiency
  - Round-trip time limits drone trajectory coordination rate, response to game dynamics
- **One decomposition:**
  - Drones form a fog network: trajectory planning, collision avoidance
  - Centralized coordination for next target location, drone function

# One Choice of Decomposition



# Coverage vs. Throughput

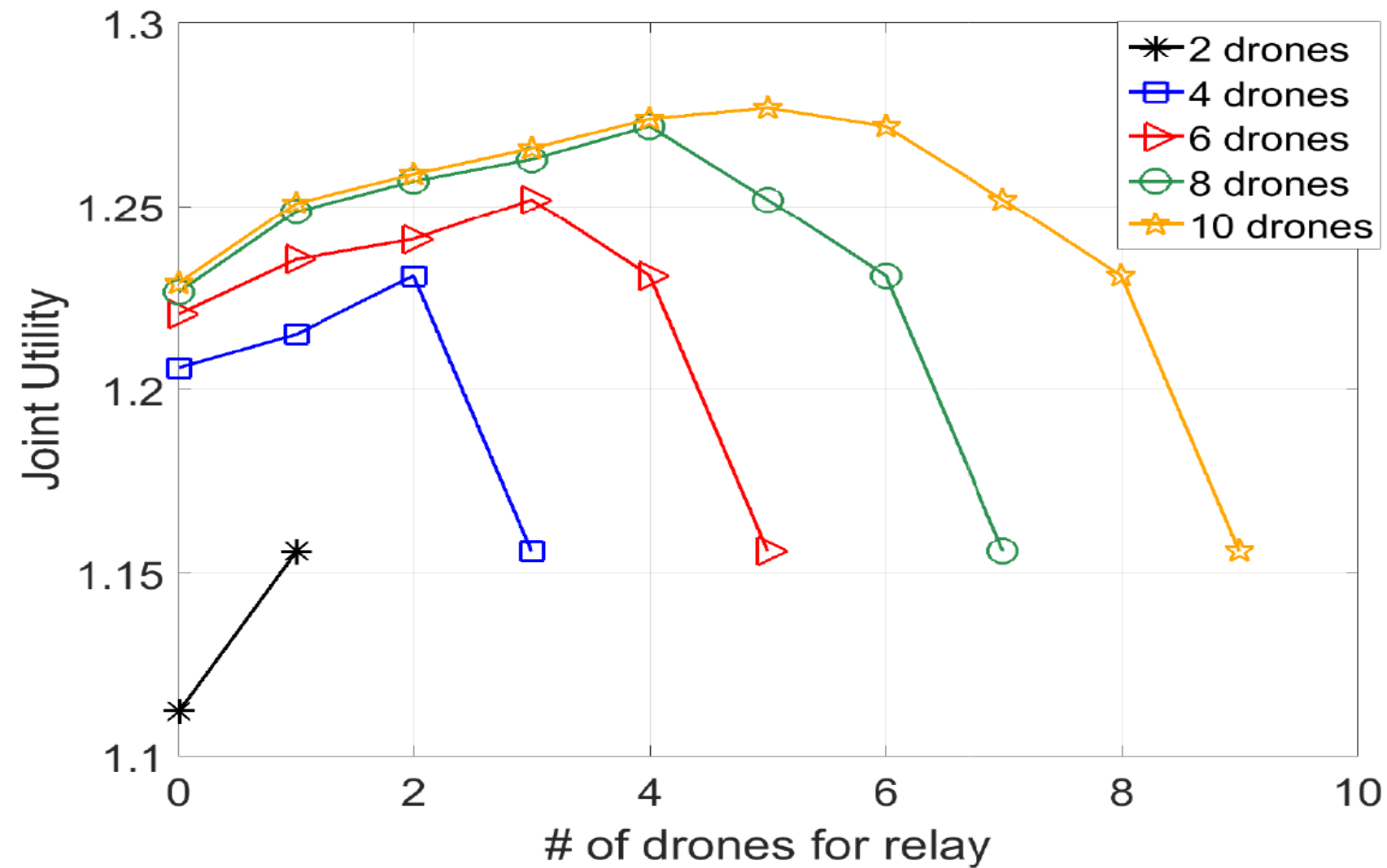


- Sensors on players/ball (location, speed)
- Predict locations of next importance scenes
- Match drones to each important scene

- Max throughput: drone selects the best server
- Throughput boosting: drone as relay



# Joint Optimization and drone allocation



Optimal allocation of drones as relay

# Observations

- A system to **coordinate a network of drones** to capture and broadcast a sports game from drone cameras over a wireless channel
- Joint Optimization
  - **Maximize the coverage of interesting scenes**: drone location assignment algorithm.
  - **Maximize video quality**: drone-server association scheme, drone as relay.
- Evaluation: optimal 4 drones for coverage, 4 as relay
  - achieve 94% coverage
  - support 2K video streaming at 20Mbps



# Personalized AR Object Placement: Where Does Learning Happen?

# Network Decomposition

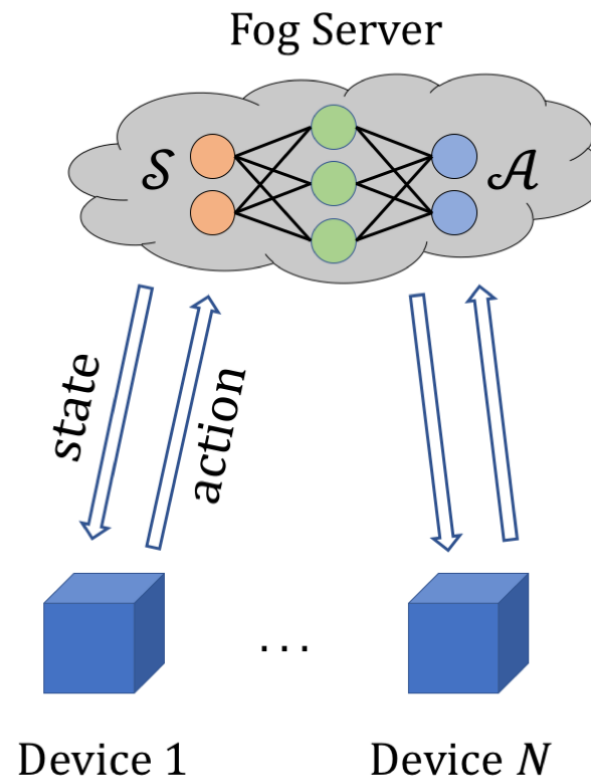
- **Policy learning phase:**

- Present users with simulated environments; collect their actions
- Use imitation learning to learn personalized hologram placements

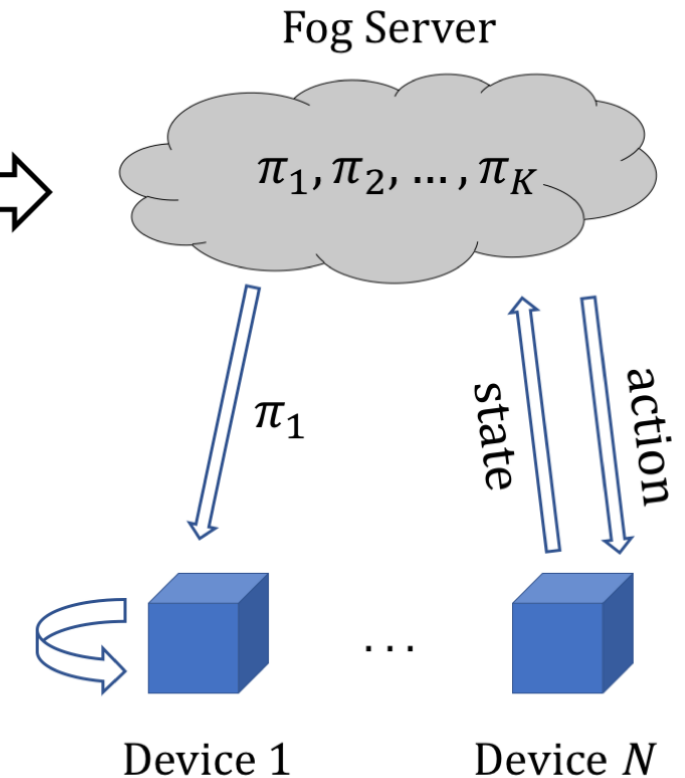
- **Policy execution phase:**

- Send to powerful devices
- Run on behalf of resource-constrained devices

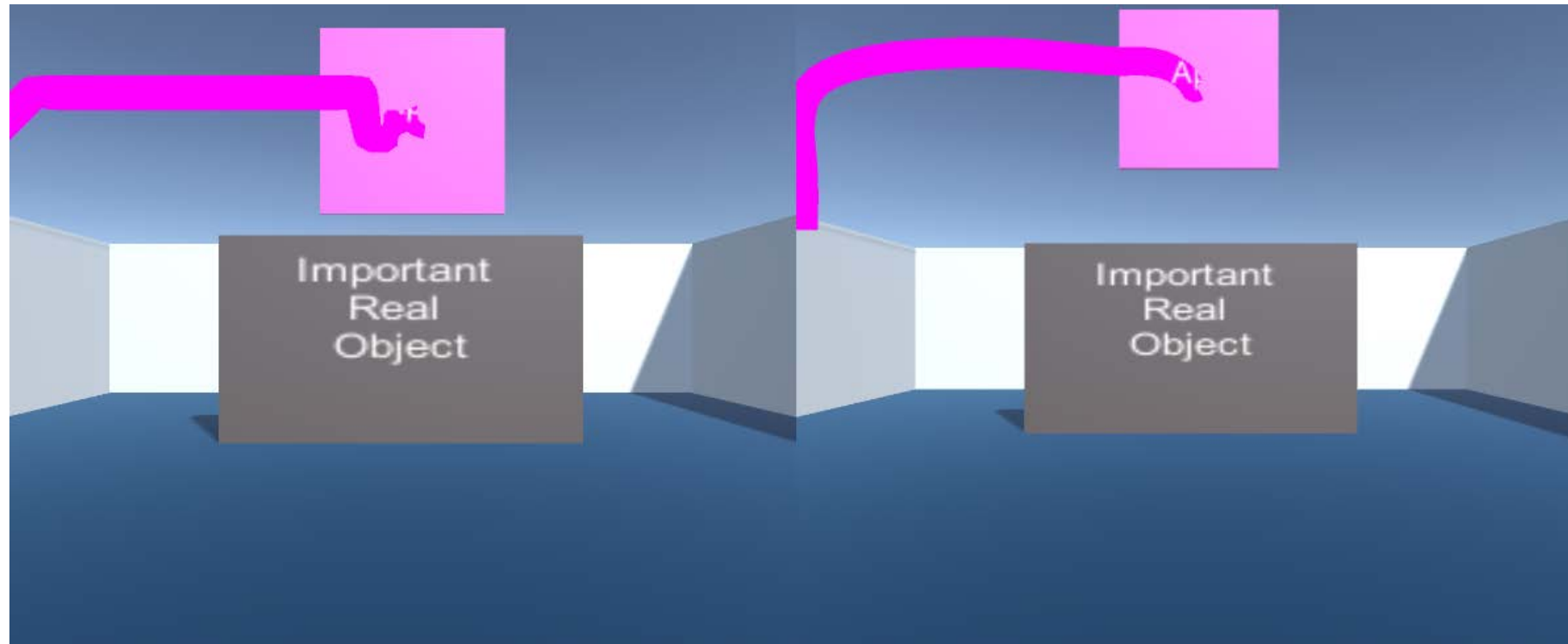
## Policy Learning Phase



## Policy Distribution and Execution Phase

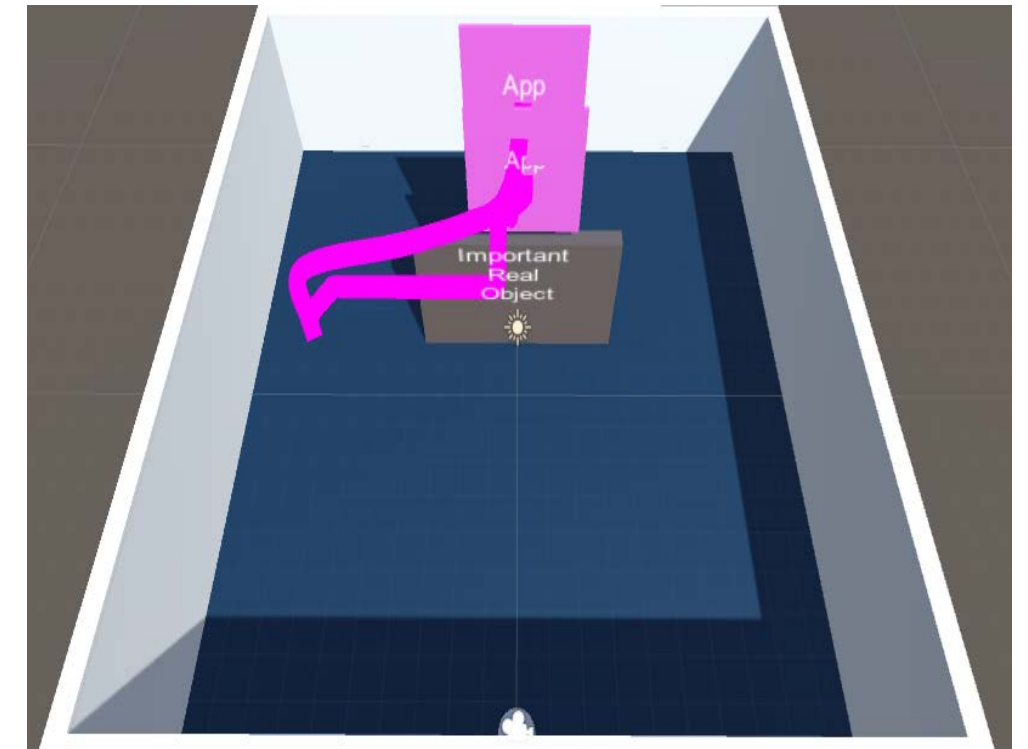


# Personalized Placement Learning



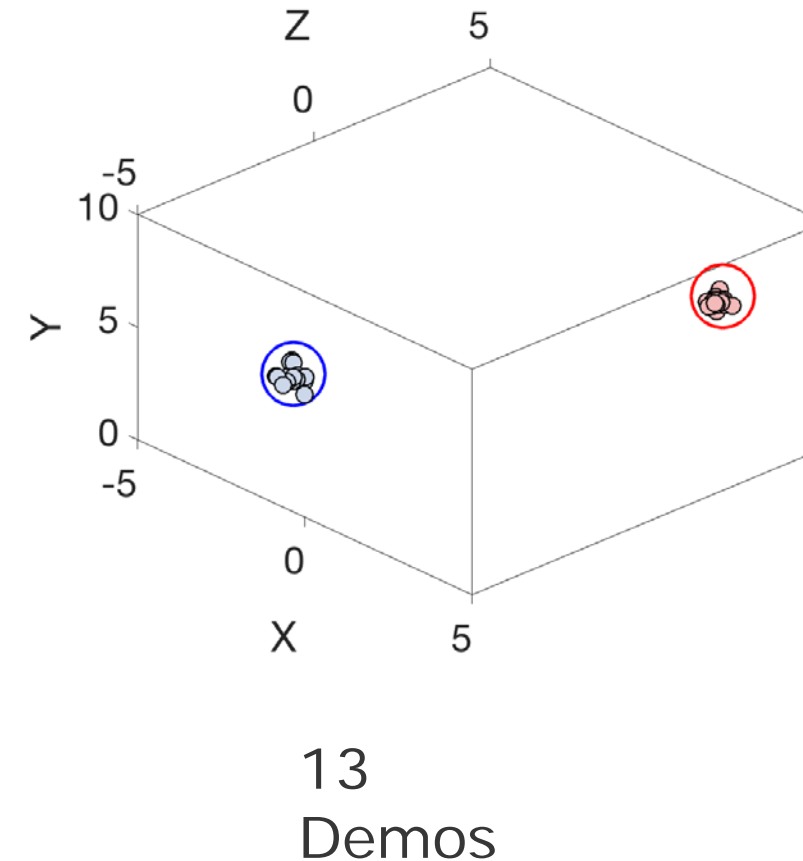
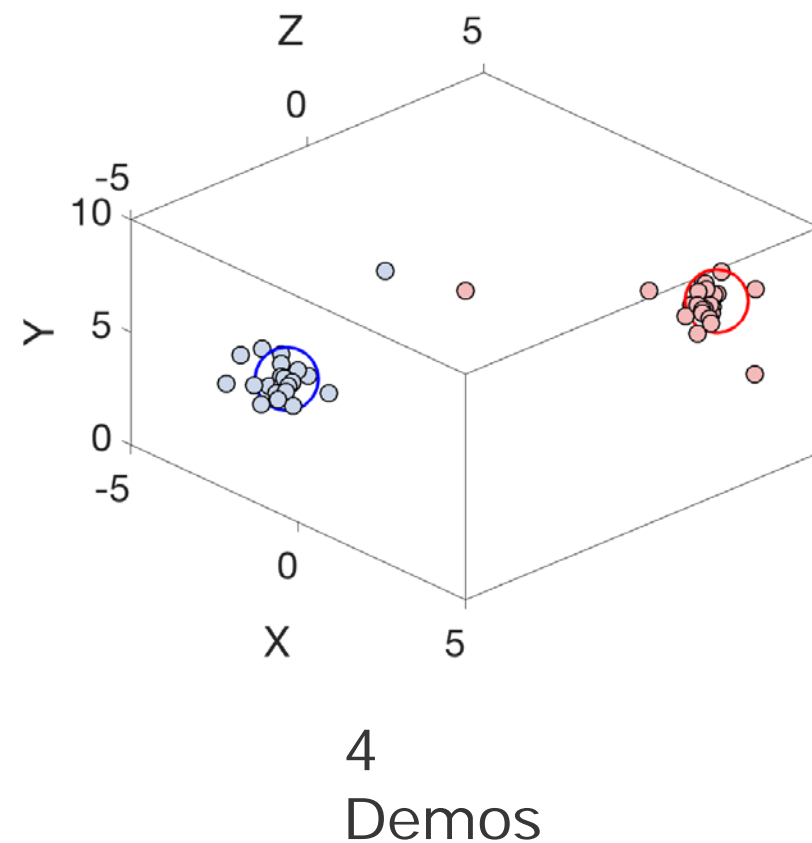
User-controlled hologram  


Agent-controlled hologram



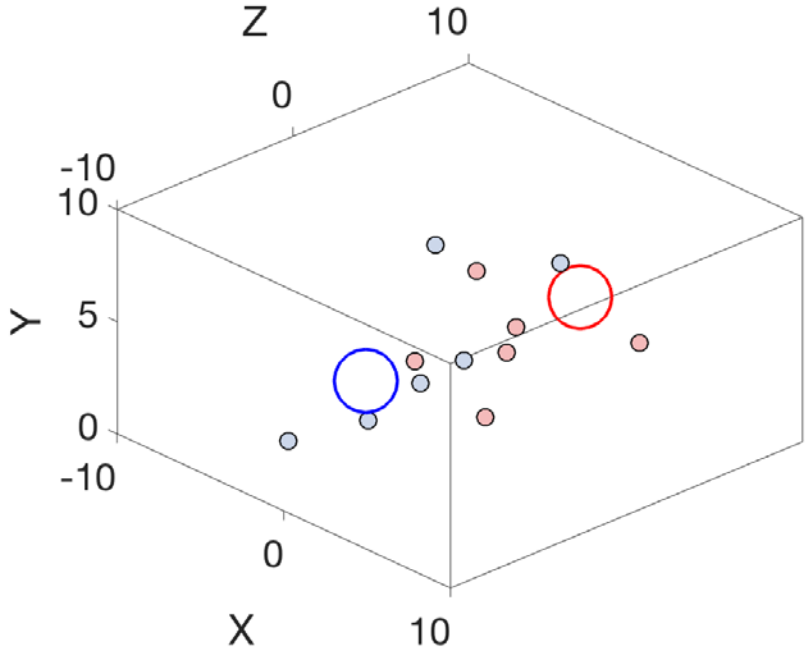
Birds-eye view shows matching trajectories in addition to placements

# Learning A User's Preference Fast

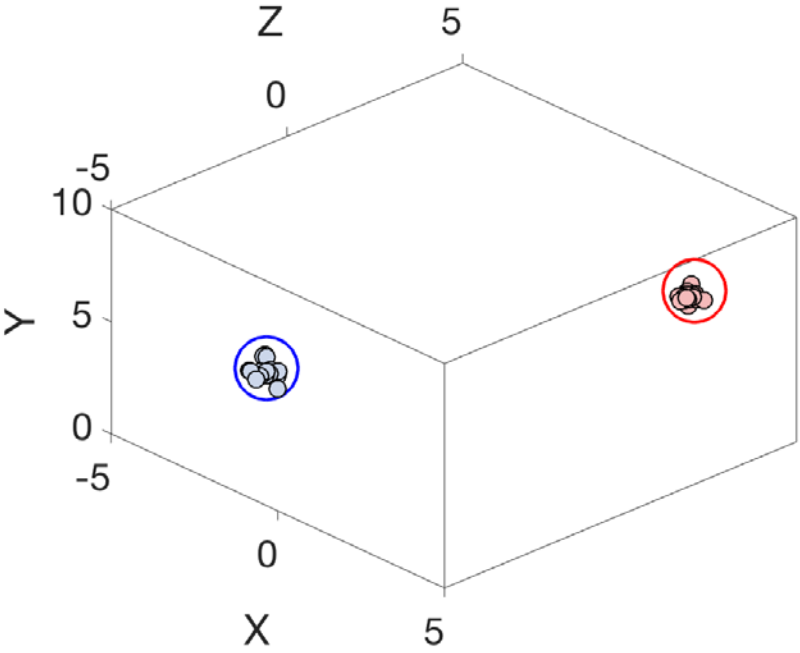


Each circle represents the users' desired destination. Dots represent algorithm's action. As early as 13 demos, agent achieves accuracy.

# State Space Reduction Helps



Full image as state



Reduced state-space

Hologram destinations after 12 trials when using the full AR image as the state. Compared with the reduced state-space there is degradation in accuracy.

# Overarching Questions

- **Where** to place a function/data set?
- What is the **interface** among modules?



# The Edge/Fog Advantage: SCALE

- Security
- Cognition
- Agility
- Latency
- Efficiency

Thank you!

