

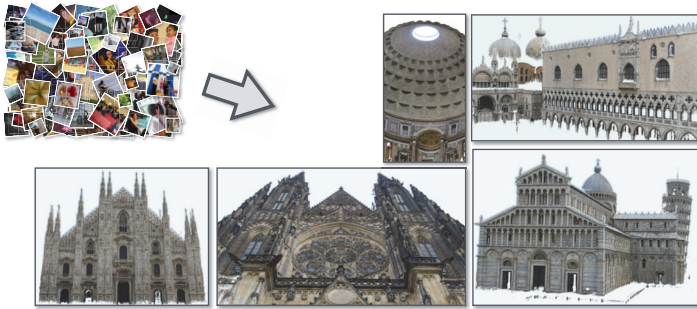


<https://colmap.github.io>

Source Code | Documentation | Tutorial | Examples

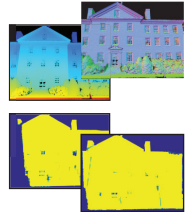
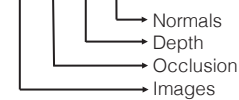
Overview

This work presents an **open source Multi-View Stereo** system for **robust** and **efficient** dense modeling from **unstructured image collections**. Experiments on benchmarks and large-scale Internet photo collections demonstrate **state-of-the-art performance** in terms of accuracy, completeness, and efficiency.



Joint Depth - Normal - Occlusion Inference

• Joint likelihood function $P(\mathbf{X}, \mathbf{Z}, \theta, \mathbf{N})$



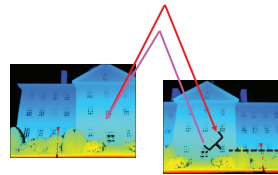
• Generalized Expectation Maximization (GEM)

- *E-Step*: Infer \mathbf{Z} using variational inference
- *M-Step*: Infer θ, \mathbf{N} using PatchMatch sampling

Contributions

- **Joint depth - normal - occlusion inference** embedded in improved PatchMatch sampling scheme
- **Pixelwise view selection** using photometric and geometric priors
- **Multi-view geometric consistency** for simultaneous refinement and image-based fusion
- **Graph-based filtering and fusion** of depth and normal maps

Multi-View Geometric Consistency



Cost function

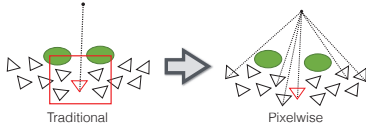
$$\xi_l^m = 1 - \rho_l^m + \eta \min(\psi_l^m, \psi_{\max})$$

Photometric Geometric

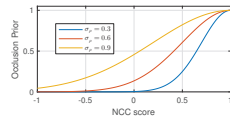
Optimization $\operatorname{argmin}_{\theta_l^m, \mathbf{n}_l^m} \frac{1}{|S|} \sum_{m \in S} \xi_l^m(\theta_l^m, \mathbf{n}_l^m)$

Pixelwise View Selection

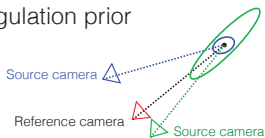
• Occlusion prior



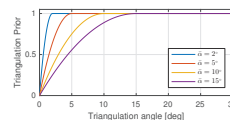
$$P(X_l^m | Z_l^m, \theta_l) = \begin{cases} \frac{1}{\sqrt{\pi}} \exp\left(-\frac{(1-\alpha_l^m(\theta_l))^2}{2\sigma_l^2}\right) & \text{if } Z_l^m = 1 \\ \frac{1}{\sqrt{\pi}} U & \text{if } Z_l^m = 0 \end{cases}$$



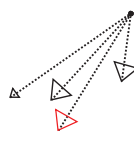
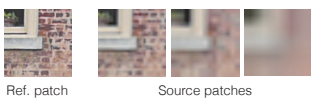
• Triangulation prior



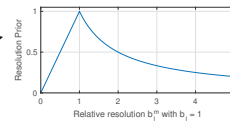
$$P(\alpha_l^m) = 1 - \frac{(\min(\hat{\alpha}_l^m, \alpha) - \alpha)^2}{\alpha^2}$$



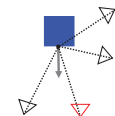
• Resolution prior



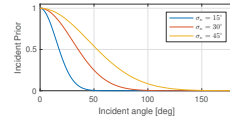
$$P(\beta_l^m) = \min(\beta_l^m, (\beta_l^m)^{-1})$$



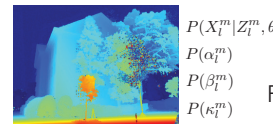
• Incident prior



$$P(\kappa_l^m) = \exp\left(-\frac{\kappa_l^m{}^2}{2\sigma_l^2}\right)$$

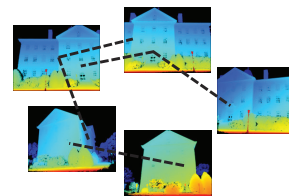
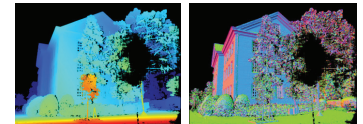


Filtering and Fusion



$P(X_l^m | Z_l^m, \theta_l)$
 $P(\alpha_l^m)$
 $P(\beta_l^m)$
 $P(\kappa_l^m)$

Filtering



Fusion



Results

